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## Advanced Robotic Programming with the MHJF

### **COURSE OUTLINE**

Catalogue Number	77-5002-0000
Category	Robotics
Duration	15 Hours
Additional Content with Hardware Package	10 Hours
Prerequisite Course	Fundamentals of Robotics with the MHJF

Note: Activities written in italics require hardware. See the Course Materials document and the individual lab activity documents for details.

#### **Activity 1: Onwards and Upwards**

- Review of Basic Robotic Programming Review of RoboCell A Look Back at the MHJF Safety Considerations **Activity 2: Programming with Subroutines** Subroutines Task: Running RoboCell and Recording Positions Subroutine Commands Task: Programming with Subroutines
  - Task: Running and Evaluating the Program
  - Task: Changing the Order in Which Subroutines are Run

#### Lab Activity A: Connecting Peripheral Devices

#### **Activity 3: Digital Inputs**

Inputs and Outputs Manually Switching Digital Inputs Jump To Command Programming with Labels and Unconditional Jumps Conditional Jump Command Task: Programming with Inputs and Conditional Jumps



#### **Activity 4: Digital Outputs**

Inputs and Outputs Experiment Table

Task: Sending Output Signals Manually

Task: Programming with Output Signals

Task: Producing Output Signals During a Robot Operation

#### Lab Activity B: Inputs and Outputs

#### **Activity 5: Extending the Envelope**

Robot Work Envelope The Rotary Table Using a Rotary Table to Stack Cylinders Implementing a Sensor Other Peripheral Devices

#### **Activity 6: The Linear Slidebase**

Introducing the Linear Slidebase Controlling the Slidebase Recording Peripheral Positions Task: Moving a Robot Along a Slidebase Task: Recording Positions for the Robot on a Slidebase Task: Programming with the Slidebase

#### Activity 7: Delivering Materials with a Conveyor Project

Conveyors in Robotic Workcells

Polling

Delivering Materials with a Conveyor

Stop Conveyor and Start Conveyor Commands

Task: Announcing the Arrival of an Object on the Conveyor

Task: Teaching Positions and Programming

Task: Running and Evaluating the Program

#### **Activity 8: Conditional Branching**

Review of Inputs and Outputs

Conditional Branching



Task: Recording Positions for a Sorting Program Task: Programming a Sorting Task

Task: Running and Evaluating the Sorting Program

#### Lab Activity C: Conditions

#### **Motoman Mini-Activity: Teaching Conditions**

Special Play Settings Teach Condition Settings Quiz

**Activity 9: The Interrupt Function** 

Review of Conditional Branching Storing Equipment Using the If Input Command Sampling Inputs On Input Interrupt # On Jump Command Task: Running RoboCell and Recording Positions Task: Programming Task: Running and Evaluating the Program

#### **Activity 10: Loops and Counters**

Jumps The Set Variable Task: Using a Variable Value to Program Conditional Jumps Using a Conditional Loop Task: Using a Conditional Loop Task: Using Controller Inputs in a Conditional Loop Programming Challenge: Combining Conditions

#### Lab Activity D: Counting Blocks

#### Lab Activity E: Shifting

#### Activity 11: Programming a Sorting System Project

Sorting Blocks from a Conveyor Gripper Sensor Task: Recording Positions Task: Programming the Variables



Task: Writing the Program Task: Running the Program Lab Activity F: Advanced Tool Settings Lab Project I: Background Task Lab Project II: Catch & Dip Lab Project III: Double Tool