

Process Control: Flow

Catalogue Number	77-3043-0002
Category	Process Control
Duration	15 Hours

Activity 1: Introduction to Process Control

What is Process Control?

What is a Control Mechanism?

Flow Rate

What is a Controller?

Manual and Automatic Flow Control Systems

The Need for Controlling Systems

Activity 2: Introduction to ProcessMotion Simulation Software

ProcessMotion Software

ProcessMotion Panel

Simulation Software

Manipulating the ProcessMotion Panel Display

Task: Running ProcessMotion and Opening Multiple Displays

Review of Process Control

Task: Running an Experiment

Output Analysis

Task: Analyzing the Output Graph

Experimenting with an Ineffective Controller

Interpreting the Output Graph

Experimenting with an Effective Controller

Task: Experimenting with an Effective Controller

Interpreting the Output Graph



Activity 3: Block Diagrams and Gain

Systems and Control Systems

Sample Control Systems

Block Diagrams

Open Loop Control Systems and Gain

Testing a Control System

Task: Testing a Control System

Testing Another Control System

Activity 4: The System Block Diagram and the Final Control Element Gain

Review of Gain

ProcessMotion Panel Control System

Task: Constructing the Block Diagram of the System

The Structure and Functioning of the Pump

Final Control Element Gain to the ProcessMotion System

Calculating the Final Control Element Gain

Task: Determining the Pump Gain

Task: Recording the Data

Task: Calculating the Pump Gain

Activity 5: Calculating Process Gain

Review of Gain

Defining Process Gain of the ProcessMotion System

Calculating the Process Gain Analytically

Determining the Process Gain Experimentally

Task: Determining the Process Gain

Task: Recording the Results

Task: Changing the Resistance of the Load Value

Task: Calculating the Process Gain Values

Experiment Conclusions

Task: Calculating Process Gain Analytically



Activity 6: First Order Systems

Steady State Response

Dynamic Response

The Time Constant

First Order Systems

First Order System Laplace Transforms

Step Inputs

First Order System Response to a Step Input

Notes on the Time Constant

Task: Constructing a Graph of System Response to a Step Input

Task: Interpreting a System Response Graph

Activity 7: The Flow System Time Constant

Review of the Time Constant

The System Order of the Flow System

Task: Measuring the Time Constant of the Flow System Experimentally

Task: Recording the Data

Activity 8: Controlling the Flow System Using Open Loop Control

Categorizing Control Systems

Closed Loop Control

Open Loop Control

Controlling the Flow System Using Open Loop Control

Task: Using Open Loop Control to Control the Flow Rate into the Tank

Task: Recording the Data

Task: Controlling the Flow System with the Load Valve Open

Task: Recording Data

Experiment Conclusions

Task: Investigating the Effect of an External Load on the Flow System Under Open Loop

Control

Task: Adjusting the Pump Setting

Results and Conclusions



Activity 9: Introduction to On-Off Control

Open and Closed Loop Control Systems

Closed Loop Control Systems

On-Off Control Algorithm

Task: Analyzing a Control System

Applying On-Off Control

On-Off Control Using Dead Band

Tolerance

Activity 10: On-Off Control - Tasks

On-Off Control

Step Inputs

Task: Step Inputs

Task: Calculating General System Information

System Behavior

Task: Calculating the System Output Over Time

The Descent of the System Response

Task: Plotting the System Descent

Investigating the Effects of Changing the Dead Band

Task: Investigating the Effects of Changing the Dead Band

Activity 11: Controlling the Flow System Using On-Off Control

Review of Open Loop Control of the Flow System

On-Off Control of the Flow System

Task: Controlling the Flow System Using On-Off Control

Analysis of the System Output

Task: Analysis of the Output Graph

Task: Completing the Experiment

Analysis of the Experiment Results

Experiment Conclusions



Activity 12: Proportional Control

Proportional Control Algorithm

Saturation

Proportional Band

Steady State System Characteristics Under Proportional Control

Dynamic System Characteristics Under Proportional Control

Activity 13: First Order Systems Under Proportional Control

Review of Proportional Control

System Response to a Step Input

Task: Calculating Time Values

Task: Calculating the System Output for Kc = 0.5

Task: Calculating the System Output for Kc = 1

Task: Calculating the System Output for Kc = 2

Task: Calculating the System Output for Kc = 4

Task: Calculating the System Output for Kc = 10

Activity 14: Controlling the Flow System Using Proportional Control

Materials

Review of On-Off Control of the Flow System

Proportional Control of the Flow System

Task: Controlling the Flow System Using Proportional Control

Task: Recording the Experiment Results

Task: Testing Other Set Point Values

Task: Controlling the Flow System for a New Value of Kc

Task Recording the Experiment Results

Task: Testing Other Set Point Values

Results and Conclusions

Task: Controlling the Flow System with Proportional Control in the Presence

of an External Load

Task: Recording the Experiment Results

Results and Conclusions

Task: Measuring the Effect of Kc on the Nature of System Response

Task: Recording the Data



Activity 15: Proportional Integral Control

First Order Systems Under Proportional Control

Higher Order Systems Under Proportional Control

Integral Control

Proportional Integral Control

Task: Constructing a Graph of the Output of a PI Controller

How Integral Control Eliminates Offset

Disadvantages of PI Control

Applying Laplace Transform to PI Control

Activity 16: Controlling the Flow System Using Proportional Integral Control

Review of Proportional Control

Controlling the Flow System Using PI Control

Task: Controlling the Flow System Using PI Control

Task: Recording the Data

Task: Controlling the Flow System with Proportional Integral Control

Experiment 1: Results and Conclusions

Task: Investigating PI Control in the Presence of an External Load

Task: Recording the Data

Task: Completing the Experiments

Experiment 2: Results and Conclusions

Activity 17: PID Control

Review of Proportional Control

Review of Proportional Integral Control

Derivative Control

Advantages of Applying a Derivative Action to a PI Controller

Proportional Integral Derivative Control

Demonstrating PID Control

Task: Investigating the Effect of Changing PID Parameters

Task: The Effect of Changing the Value of Kc

Task: The Effect of Changing the Value of Ti

Task: The Effect of Changing the Value of Td



Activity 18: Controlling the Flow System Using Proportional Integral Derivative Control

Review of P and PI Control

Control of Higher Order Systems

Review of PID Control

Task: Controlling the ProcessMotion Flow System with a PID Controller

Task: Recording Data

Task: Completing the Experiments

Results and Conclusions

Task: Investigating the Effect of PID Control on a Higher Order System

Task: Adjusting the Value of Kc When Using P Control

Task: Adjusting the Value of Ti When Using PI Control

Task: Adjusting the Value of Td When Using PID Control

Activity 19: Controller Selection and Design

Designing a Control System

Stage 1: Selecting an Appropriate Control Algorithm

Stage 2: Determining the Correct Parameters

Stage 3: Fine Tuning

Setting the Parameters for a PID Control System

Task: Determining the Critical Gain Value

Task: Determining the Cycle Time

Task: Fine-tuning the PID Controller

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Activity 20: Designing Controllers for the Flow System

Review of the Controller Design Process

Designing a Controller for the Flow System: 1

Task: Experimenting with the Controller

Task: Examining the Controller Performance

Task: Evaluating the Controller Performance

Designing a Controller for the Flow System: 2

Task: Testing the Controller

Task: Examining the Controller Performance

Task: Evaluating the Controller Performance

Experiment Results

Designing a Controller for the Flow System: 3

Task: Testing the Controller

Task: Examining the Controller Performance

Task: Evaluating the Controller Performance

Experiment Results

Post-test